

## DAFTAR PUSTAKA

- Bradski, G., & Kaehler, A. (2008). Learning OpenCV. In *Learning OpenCV*.  
<http://shop.oreilly.com/product/0636920022497.do>
- Budiarto Hadiprakoso, R., & Buana, I. K. S. (2021). Deteksi Serangan Spoofing Wajah Menggunakan Convolutional Neural Network. *Jurnal Teknik Informatika Dan Sistem Informasi*, 7(3), 618–626.  
<https://doi.org/10.28932/jutisi.v7i3.4001>
- Distante, A., & Distante, C. (2020). Handbook of Image Processing and Computer Vision. In *Handbook of Image Processing and Computer Vision* (Vol. 3).  
<https://doi.org/10.1007/978-3-030-42378-0>
- Fusiello, A. (2000). Uncalibrated Euclidean reconstruction: A review. *Image and Vision Computing*, 18(6), 555–563. [https://doi.org/10.1016/S0262-8856\(99\)00065-7](https://doi.org/10.1016/S0262-8856(99)00065-7)
- Heikkila, J., & Silven, O. (1997). Four-step camera calibration procedure with implicit image correction. *Proceedings of the IEEE Computer Society Conference on Computer Vision and Pattern Recognition*, 1106–1112.  
<https://doi.org/10.1109/cvpr.1997.609468>
- Jia, Z., Yang, J., Liu, W., Wang, F., Liu, Y., Wang, L., Fan, C., & Zhao, K. (2015). Improved camera calibration method based on perpendicularity compensation for binocular stereo vision measurement system. *Optics Express*, 23(12), 15205. <https://doi.org/10.1364/oe.23.015205>
- Khan, A. A., Laghari, A. A., & Awan, S. A. (2021). EAI Endorsed Transactions Machine Learning in Computer Vision : A Review. *EAI Endorsed Transactions on Scalable Information Systems*, 8(32), 1–11.
- Liu, X., Tian, J., Kuang, H., & Ma, X. (2022). A Stereo Calibration Method of Multi-Camera Based on Circular Calibration Board. *Electronics (Switzerland)*, 11(4). <https://doi.org/10.3390/electronics11040627>
- Loop, C., & Zhang, Z. (1999). Computing rectifying homographies for stereo

- vision. *Proceedings of the IEEE Computer Society Conference on Computer Vision and Pattern Recognition*, 1, 125–131.  
<https://doi.org/10.1109/cvpr.1999.786928>
- Nedevschi, S., Marița, T., Vaida, M.-F., Danescu, R. G., Frentiu, D., Oniga, F., Pocol, C., & Daicoviciu, C. (2002). Camera Calibration Method for Stereo Measurements. *Journal of Control Engineering and Applied Informatics*, 4, 21–28. <https://api.semanticscholar.org/CorpusID:34764036>
- Remondino, F., & Fraser, C. (2006). *Digital Camera Calibration Methods* : 5, 266–272.
- Rivki, M., Bachtiar, A. M., Informatika, T., Teknik, F., & Indonesia, U. K. (n.d.). *Implementasi Metode Zhang Pada Kalibrasi Kamera Untuk Estimasi Jarak Pada Obyek Bergerak*. 112.
- Senju, A., & Johnson, M. H. (2016). On Plane-Based Camera Calibration: A General Algorithm, Singularities, Applications Peter. *Behavioral and Brain Sciences*, 33(6), 458–459.
- Steinke, D., McKeown, J. T. A., Zyba, A., McLeod, J., Feng, C., & Hebert, P. D. N. (2024). Low-cost, high-volume imaging for entomological digitization. *ZooKeys*, 1206, 315–326. <https://doi.org/10.3897/zookeys.1206.123670>
- Sultana, S., Alam, M., Su'ud, M., Mustapha, J., Prasad, M., Practices, T.-, 56, V.-, 10.1145/3648357, D.-, -, J., & -, E. (2024). A Flexible New Technique.pdf. *ACM Computing Surveys*, 10(56).
- Urip, T., Adi, K., Catur, D., & Widodo, E. (2017). Pengukuran jarak objek pejalan kaki terhadap kamera menggunakan kamera stereo terkalibrasi dengan segmentasi objek histogram of oriented gradient. *Youngster Physics Journal*, 6(3), 249–262.
- Verri, A., Fusiello, A., & Trucco, E. (2000). A compact algorithm for rectification of stereo pairs. *Machine Vision and Applications*, 12(1), 16–22.
- Villalba-Diez, J., Schmidt, D., Gevers, R., Ordieres-Meré, J., Buchwitz, M., & Wellbrock, W. (2019). Deep learning for industrial computer vision quality

control in the printing industry 4.0. *Sensors (Switzerland)*, 19(18), 1–23.  
<https://doi.org/10.3390/s19183987>

Weatherbee, W. J., Fowler, J., & Van Proosdij, D. (2023). Automated rapid artefact surface area measurement from imagery with computer vision. *Journal of Lithic Studies*, 10(1). <https://doi.org/10.2218/jls.5623>